Affectation des articles à présenter :
Présentation de 15 à 20 min
Faire ressortir les idées principales, les verrous, la méthodologie ainsi que les résultats
(Pas de résumé du papier)

Cattelain
A survey of socially interactive robots :
Web-Based Telerehabilitation for the Upper Extremity After Stroke

Drissi
Emotion and sociable humanoid robots

Valentin :
Tracking Human Motion and Actions for Interactive Robots :

Roux
Tracking Human Motion and Actions for Interactive Robots :

Khaldi
Tracking Human Motion and Actions for Interactive Robots :

Ruquois :
MOBILE ROBOTIC TOYS AND AUTISM
Enjoyment, Intention to Use and Actual Use of a Conversational Robot by Elderly People

Aly :
How social robots will help us to diagnose, treat, and understand autism

Eyzat
A Storytelling Robot for Pediatric Rehabilitation

Nallanathan
A Storytelling Robot for Pediatric Rehabilitation

Bailleux
Providing Route Directions: Design of Robot’s Utterance, Gesture, and Timing
Cherpin  
How People Talk When Teaching a Robot

Bblanc  
Providing Route Directions: Design of Robot’s Utterance, Gesture, and Timing

Abou hala  
Providing Route Directions: Design of Robot’s Utterance, Gesture, and Timing

Delaheche  
Attention via Synchrony: Making Use of Multimodal Cues in Social Learning  
An approach to multi-modal human-machine interaction for intelligent service robots

Diop  
Multi-modal sensor fusion using a probabilistic aggregation scheme for people detection and tracking  
An approach to multi-modal human-machine interaction for intelligent service robots

Brzek  
A Dancing Robot for Rhythmic Social Interaction

Khalidi  
A Dancing Robot for Rhythmic Social Interaction

Leclercq :  
How People Talk When Teaching a Robot

Aguilar  
Affective social robot